Ultrasonic velocity and attenuation of glass ballotini in viscous and viscoelastic fluids

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Measurements are reported of the attenuation, α , and the velocity, c, of 1–5 MHz compressional wave ultrasound in suspensions of glass ballotini in Newtonian and non-Newtonian base fluids. For the Newtonian fluids, good agreement is found between the measured α and c, and the α and c obtained from the Urick and the Ament expressions, using the same value for the base fluid's viscosity. For the non-Newtonian base fluids, this agreement was absent. The existence of shear elasticity G in these fluids is suggested to explain the results. By incorporating elasticity into the Urick and the Ament theories the disagreement is resolved, and values of G are found which are in order-of-magnitude agreement with those found at the same frequency by another method. A test is proposed of a recent assertion that simple molecular fluids possess a shear elasticity.

Keywords: fluids; glass ballotini; velocity; attenuation

The use of ultrasound to characterize suspensions is a large and growing application, as recently reviewed by McClements¹. Despite this, there have been relatively few basic and quantitative investigations, where the ultrasonic propagation parameters such as velocity (c)and attenuation (α) have been measured for wellcharacterized suspensions, and the results compared with theoretical expressions. One of our aims was to use ultrasonics to probe the rheology of fluids. This required a granular rather than colloidal particle size, i.e. particles of about 10–100 μ m in diameter. Here, the thermal scattering contribution to the attenuation was negligible, leaving the visco-inertial scattering term dominant such that α and c were sensitive to the local rheology of the fluid surrounding the particles. To ensure dominance of the visco-inertial contribution, a significant density difference between the particles and the surrounding fluid was necessary. This constraint, and that of the large diameters required relative to the commonly available polymer latices, disallowed the use of accurately monodisperse particles. Hence, glass ballotini, sieved into narrow particle size fractions and sized by light scattering and optical microscopy, were used.

Work similar to ours, and using the same ballotini, was reported by Rahalkar *et al.*², who studied the effects of adding ballotini to aqueous solutions of a xanthan polymer. Their results agreed only qualitatively with existing theories for suspensions. They attributed this to the viscoelasticity of the polymer gel network.

Drilling muds are a suspension of mineral grains in a non-Newtonian base fluid, typically a polymer or clay gel. The network's yield stress is designed to prevent sedimentation of granular particles such as barite (added to increase the mud density) or rock particles (which originate from the drill bit). The ultrasonic properties of drilling mud have applications in the interpretation of signals from downhole ultrasonic tools³ and in the monitoring of mud flows⁴. The ultrasonic velocity and attenuation have been shown⁵ to be sensitive to the spontaneous gelation of drilling mud clays. Here we investigate the effects of adding granular particles to these fluids, simulating the particles of barite and rock in real drilling muds.

Theoretical details

Viscous base fluid

We assume non-interacting spherical particles, of diameter 2a, small compared with the ultrasonic wavelength λ , i.e. $2a < \lambda/10$. The Urick expression⁶ for the excess amplitude attenuation per unit volume fraction of particles ϕ is

$$\frac{\alpha}{\phi} = \frac{k^4 a^3}{6} + \frac{ks(r-1)^2}{2s^2 + 2(r+T)^2} \tag{1}$$

where $k = 2\pi/\lambda$ and $r = \rho'/\rho$ is the ratio of particle to base fluid densities. The base fluid rheology is effective through the hydrodynamic skin depth δ . For a Newtonian fluid of viscosity η ,

$$\delta = \left(\frac{2\eta}{\omega\rho}\right)^{1/2} \tag{2}$$

at a pulsatance ω . The terms T and s in Equation (1) are

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then defined by

$$T = \frac{1}{2} + \frac{9\delta}{4a} \tag{3}$$

and

$$s = \frac{9\delta}{4a} \left(1 + \frac{\delta}{a} \right) = \frac{1}{18} (2T - 1)(4T + 7)$$
(4)

For the material properties and particle diameters considered here $\delta/a < 1$, 0.2 being typical. Expanding Equation (1) in powers of δ/a to the second order gives

$$\frac{\alpha}{\phi} = \frac{k^4 a^3}{6} + \left(\frac{r-1}{2r+1}\right)^2 \frac{9k\delta}{2a} \left(1 + \frac{\delta}{a} \left(1 - \frac{18r}{(2r+1)^2}\right)\right)$$
(5)

Thus, terms in $(\delta/a)^2$ vanish when $1 = 18r/(2r + 1)^2$, giving $r = (7 \pm \sqrt{45})/4$, i.e. for r = 0.0729 or 3.427. For the ballotini ($\rho' \sim 2900$ kg m⁻³) in our base fluids ($\rho \sim 1000$ kg m⁻³) r is sufficiently close to 3.427 so that the term in $(\delta/a)^2$ contributes only a few percent to α/ϕ ; less than the experimental uncertainty. Thus, Equation (1) simplifies to

$$\frac{\alpha}{\phi} = \frac{k^4 a^3}{6} + \frac{9k\delta}{2a} \left(\frac{r-1}{2r+1}\right)^2 \tag{6}$$

Although obtained originally by Urick using a nonscattering argument, Equation (6) is identical, up to $(\delta/a)^1$, to the expression of Hay and Mercer⁷, derived on the basis of scattering theory for a solid, elastic sphere.

For the phase velocity c we use the expression of Ament^{8,9}. The phase slowness is

$$\frac{1}{c} = \sqrt{\bar{K}\rho^*} \tag{7}$$

The volume average compressibility \bar{K} is

$$\bar{K} = K'\phi + K(1-\phi) \tag{8}$$

where K' and K refer to the compressibility of the ballotini and the base fluid, respectively. The effective density is

$$\rho^* = \bar{\rho} + z \tag{9}$$

where the volume average density is

$$\bar{\rho} = \rho'\phi + \rho(1-\phi) \tag{10}$$

The base fluid rheology enters c through

$$z = -\frac{2(\rho' - \rho)^2 \phi(1 - \phi)A}{A^2 + C^2}$$
(11)

where

$$A = 2(\rho' - \rho)(1 - \phi) + 2\rho(1 + T)$$
(12)

and

$$C = 2\rho s \tag{13}$$

T and s being defined in Equations (3) and (4). Using Equations (8)–(13) and taking only terms linear in ϕ , Equation (7) gives

$$\frac{1}{\phi} \left(\frac{c_0}{c} - 1 \right) = \frac{K' - K}{2K} + \frac{3}{2} \frac{r - 1}{2r + 1} + \frac{9\delta}{2a} \left(\frac{r - 1}{2r + 1} \right)^2 \quad (14)$$

where c_0 is the velocity in the base fluid.

Viscoelastic base fluid

For a viscoelastic base fluid, the viscosity η in the previous expressions for α and c become complex. Thus, η is replaced by $\eta + iG/\omega$, where $i^2 = -1$ and G is the shear modulus of the base fluid. Hence, the skin depth δ in Equation (6) and Equation (7) also becomes complex, and is written $\delta' + i\delta''$, where δ' and δ'' are real. The complex wavevector may be written

$$\mathbf{k} = \frac{\omega}{c} + \mathrm{i}\alpha \tag{15}$$

We replace δ in Equation (6) and Equation (14) by $\delta' + i\delta''$ and use these complex versions of 1/c and α in Equation (15). Now $\omega/c = \operatorname{Re} k$ and $\alpha = -i \operatorname{Im} k$, thus

$$\frac{\alpha}{\phi} = \frac{a^3 k^4}{6} + \frac{9k}{2a} \left(\frac{r-1}{2r+1}\right)^2 (\delta' + \delta'')$$
(16)

and

$$\frac{1}{\phi} \left(\frac{c_0}{c} - 1 \right) = \frac{K' - K}{2K} + \frac{3}{2} \frac{r - 1}{2r + 1} + \frac{9}{2a} \left(\frac{r - 1}{2r + 1} \right)^2 (\delta' - \delta'')$$
(17)

Comparing Equation (16) and Equation (17) with Equation (6) and Equation (14) shows that if the base fluid acquires elasticity, the effect is to increase both α and c. It will be convenient to write

$$\delta' = \frac{\delta}{\sqrt{2}} ([1 + Q^2]^{1/2} + 1)^{1/2}$$
(18)

and

$$\delta'' = \frac{\delta}{\sqrt{2}} ([1+Q^2]^{1/2} - 1)^{1/2}$$
(19)

where $Q = G/\omega\eta$ and δ is defined in Equation (2).

Polydispersity

It was found that the particle radii (a) of the seived ballotini fitted closely a Gaussian log-normal probability function

$$f(x) = f(\bar{x}) \exp \left(\frac{\bar{x} - x}{2\sigma}\right)^2$$
(20)

where $x = \ln a$, \bar{x} is the mean logarithmic radius, and σ is the standard deviation of x about \bar{x} . The volumeaverage of functions such as a^n , where n is an integer, is then given by

$$\overline{a^n} = \int_{-\infty}^{\infty} a^n f(x) \, \mathrm{d}x \Big/ \int_{-\infty}^{\infty} f(x) \, \mathrm{d}x = (\bar{x})^n \exp(n\sigma)^2 \tag{21}$$

This result is readily applied to theoretical expressions where powers of the particle radius exist in linear combinations. Thus, using Equation (21) shows that the polydisperse version of Equation (6) becomes

$$\frac{\alpha}{\phi} = \frac{k^4 a_0^3}{6} \exp(3\sigma)^2 + \left(\frac{r-1}{2r+1}\right)^2 \frac{9k\delta}{2a_0} \exp\sigma^2$$
(22)

where a_0 is defined by $\ln a_0 = \overline{\ln a}$. Similarly, Equation (14) becomes

$$\frac{1}{\phi} \left(\frac{c_0}{c} - 1\right) = \frac{K' - K}{2K} + \frac{3}{2} \frac{r - 1}{2r + 1} + \frac{9\delta}{2a} \left(\frac{r - 1}{2r + 1}\right)^2 \exp \sigma^2$$
(23)

It is, however, not possible to write down a polydisperse version of Equation (7) with the same ease, owing to the complicated way that a enters this equation, through z. Facing the same problem, McClements¹⁰ used the Sauter mean radius. On the basis of the above, we see no justification for this approach. We appreciate however, that McClements' main interest was the variation of ultrasonic parameters with frequency, rather than particle radius, so that a satisfactory empirical correction for polydispersity may have been possible. We compared our velocity data with Equation (7), using the mean radius a_0 rather than attempting a complicated correction for polydispersity. Fair agreement between the ultrasonic and the rheologically-measured viscosities is obtained.

Apparatus

Ultrasonic measurements

Accurate measurements of α and c were required. Various methods of measuring these have been compared⁵, where it was concluded that the best methods for c and α were the pulse-echo overlap (PEO), and tone burst, respectively. These were essentially single frequency methods, and changes in the operating frequency were feasible within the range 1–5 MHz. A full description of the apparatus and method is given by Champion *et al.*⁵ The same equipment was used for the measurements described here.

Fluids and particles

The Newtonian fluids were glycerol, and a polypropylene glycol (PPG) of molecular weight 2025. Densities were measured to within ~1% using a weighing bottle. Viscosities were measured using a Haake rheometer over a temperature range of $17-23^{\circ}$ C. The viscosities were sufficiently large (~Pa s) to be able to disregard ballotini sedimentation over the measurement time.

The non-Newtonian fluids were both suspensions of bentonite clays. The water-based suspension was made by adding Bentopharm B20 (a pharmaceutical grade sodium montmorillonite: Bromhead and Denison, UK), to deionized water. A volume fraction range 0.01-0.03 gave a gelatinous suspension of yield stress sufficient to prevent sedimentation of the more dense ballotini. A rheological description of Bentopharm B20 suspensions has been given by Heath and Tadros¹¹. It was important that no air bubbles were trapped in these suspensions by the yield stress, and suspensions were de-aired for about 1 hour in a bell jar held at a pressure close to -1 bar.

The oil-based bentonite suspension was prepared by mixing Carbogel clay with Milclean oil and the appropriate surfactants. (Carbogel and Milclean are products of Milchem, USA.) This produced another gelatinous fluid which was, through its yield stress, capable of suspending ballotini particles without sedimentation.

Particles

The particles were lead glass ballotini (Jencons No. 18), of nominal diameter 40–75 μ m. Inspection by optical microscope showed excellent sphericity, and also the presence of particles in the diameter ranges 30–100 μ m. The glass density was measured on a de-aired sample, using a liquid displacement method, giving $\rho' = 2900 + 20$ kg m⁻³. This compares with 2950 kg m⁻³ given by Jencons.

Over the 30-100 μ m diameter size range, taking for example 5 MHz with glycerol as the base fluid, the dominant attenuation mechanism changes from scattering to viscous loss. For a 30 μm diameter sphere $\alpha_{sca}/\alpha_{vis} \sim$ 0.03, whereas for a 100 μ m sphere, $\alpha_{sca}/\alpha_{vis} \sim 4$. This shift from one to another mechanism was ideal for the purpose of checking the ultrasonic theories of α and c. Sieving and particle size measurement was undertaken to produce batches of well-characterized ballotini in sufficient amount for the ultrasonic measurements. A nest of Endecotts sieves was used, with sieve mesh apertures of 38, 45, 53, 63, 75, 90 and 125 μ m. The ballotini were dried at 35°C for 30 min to reduce dampness and sticking, and poured into the coarsest sieve at the top of the nest, which was tapped and shaken. Before removal from a sieve the ballotini were gently brushed across it to ensure that small particles passed through to the next sieve. Batches of 2-3 g were seived in this way to produce size fractions of smaller polydispersity than the as-received sample.

Size distribution measurements were made using a Leeds and Northrup Microtrac particle size analyser. This uses light scattering from a very dilute ($\phi \sim 10^{-4}$) dispersion in water. The Microtrac gave mean diameter, standard deviation, and a diameter distribution consisting of the relative volume of ballotini in fixed diameter ranges. The reliability of the Microtrac data was tested by comparing with data from a Seescan image analysis system. Photomicrographs of the ballotini were digitized in terms of optical density, and the data interpreted in terms of diameter distribution by the image analyser. The data points of Figure 1 compare the Microtrac with the Seescan results for the as-received ballotini. The curves of *Figure 1* are fits of the log-normal distribution to the two data sets. The close agreement between the methods suggested reliability of both, and the Microtrac method was used routinely to obtain a_0 and σ . Table 1 shows these parameters for the as-received and the sieved ballotini, where () indicates image analyser data.



Figure 1 Percentage by volume versus In(diameter [µm]) for Jencons number 18 ballotini. Upright crosses; image analysis. Diagonal crosses; light scattering

Table 1 a_0 and σ for the as-received and sieved ballotini

Sieve range (µm)	a ₀ (μm)	σ	
<19	15.8	0.3	
19–22.5	19.9	0.25	
22.5-26.5	25.0	0.24	
26.5-31.5	28.1	0.24	
31.5-37.5	31.3	0.27	
37.5-45.0	40.4	0.29	
45.0-62.5	44.3	0.33	
as-received	31.5 (30.5)	0.41 (0.35)	

Results

Newtonian fluids

Attenuation. Preliminary measurements were made to establish the range of validity of the theory, i.e. where $\alpha \propto \phi$. Figure 2 shows that $0 < \phi < 0.03$ allows both linearity, and also an α large enough to obtain good data. Measurements of α/ϕ were then made for the various sieved fractions of Table 1. Figure 3 shows data at 5 MHz, together with a line described by Equation (22). As the least well-defined quantity of Equation (22) was σ , the data points and the theoretical line in Figure 3 were fitted by assuming σ to be constant throughout the sieved fractions, and allowing it to vary to obtain the best fit. The resulting $\sigma = 0.21 \pm 0.04$ was in good agreement with the Microtrac particle size analysis of Table 1. In the above comparison the largest value of λ/a_0 was about 0.1, for which the dipole scattering (Rayleigh region) approximation incorporated into Equation (6) and Equation (22) should be good. Trespass into the above-Rayleigh region is shown by the divergence of data from theory (Equation 22) in Figure 4. Here, a poor fit between data and the prediction of Equation (22) is seen to occur at $a_0 > 30$, corresponding to $a_0/\lambda \sim 0.1$. Below this, the fit between data and Equation (22) is seen to be good. The limit found above agrees well with the estimate of $a_0/\lambda = 0.1$ of Allegra and Hawley¹², found by calculating the scattering terms of α for Rayleigh spheres and above. Data and theory (Equation 22) are further compared in Figure 5. At a frequency of 2.25 MHz and using PPG 2025 as the base fluid, $a_0/\lambda < 0.07$ for all ballotini, and the fit is seen to be good.

Velocity. Figure 6 shows the measured velocity (c) data at 1 MHz versus volume fraction ϕ for the smallest sieved ballotini fraction, $a_0 = 15.8 \ \mu\text{m}$. The broken curve shows the prediction of Equation (7) if $\eta = 1.33 \pm 0.1$ Pa s is used for the fit, i.e. that of glycerol at the temperature (20°C) of measurement. If η in Equation (7) is assumed to be the macroscopic viscosity of the suspension it can be described by

$$\eta = \eta_0 (1 + K_2 \phi + K_3 \phi^2) \tag{24}$$

where the classical Einstein result is $K_2 = 5/2$, and the magnitude of K_3 depends on the nature and the state of the suspension. We may neglect Brownian motion for even the smallest diameter ballotini, and ultrasonic fields imply a high frequency, low shear, oscillatory flow. For these conditions $K_3 = 5.2$ has been derived^{13,14}. Using Equation (24) with $K_3 = 5.2$ for η in Equation (7) gave the solid line in *Figure* 6 where $\eta_0 = 2.1 \pm 0.1$ Pa s. Thus, the fit to data is much improved compared with taking a ϕ -independent base fluid viscosity, and a fair agreement is found between η_0 and the viscosity η of the base fluid.



Figure 2 Attenuation versus ballotini volume fraction for unsieved ballotini at 20°C. Solid curve (left ordinate); glycerol at 5 MHz. Broken curve (right ordinate); PPG 2025 at 2.25 MHz



Figure 3 Excess attenuation versus mean radius a_0 for ballotini of $\phi = 0.0124$ in 95% by volume glycerol aqueous solution at 20°C and 5 MHz



Figure 4 Excess attenuation versus mean radius a_0 for ballotini of ϕ = 0.01 in PPG2025 at 20°C and 5 MHz



Figure 5 Excess attenuation versus mean radius a_0 for ballotini of $\phi = 0.01$ in PPG 2025 at 20°C and 2.25 MHz



Figure 6 Velocity versus ballotini volume fraction for $a_0 = 15.8 \,\mu\text{m}$ ballotini in glycerol at 20°C and 1 MHz



Figure 7 Velocity versus ballotini volume fraction for $a_0 = 15.8 \,\mu\text{m}$ ballotini in glycerol at 20°C and 5 MHz

Measurements were made of c for the same ballotini fraction at 5 MHz, the data being shown in *Figure 7*. The solid curve shows an excellent fit to the data if η was allowed to vary with ϕ according to Equation (24) with $K_3 = 5.2$; a base fluid viscosity of 1.30 Pa s was obtained for η_0 , compared with 1.33 Pa s measured rheometrically. The broken line shows the inferior fit to data if $\eta = 1.33$ Pa s is assumed, constant with ϕ .

At 2.25 MHz the data for $c(\phi)$ are shown in Figure 8. The solid curve shows the fit to the data allowing η to vary according to Equation (24) with $K_3 = 5.2$, giving $\eta_0 = 1.0 \pm 0.1$ Pa s. The broken curve fits Equation (7) to the data assuming a ϕ -independent $\eta = 1.33$ Pa s. Again the fit is much improved by the procedure of allowing η to vary with ϕ .

Shear rheology

We have shown, above, the validity of Equation (22) for α at low volume fractions ($\phi < 0.03$), and also that of Equation (7) for c at high volume fractions if the base fluid viscosity is assumed to vary with ϕ according to well-founded expectations of the effect of particle concentration on the bulk fluid rheology. In this section we use measurements of α and c to obtain the shear viscosity, and elasticity, of fluids surrounding the ballotini.

Newtonian base fluids. Using as-received, unsieved, ballotini, measurements were made of α at 2.25 MHz over the range $0 < \phi < 0.03$, using PPG 2025 as the base fluid, and obtaining η using Equation (22). Similar measurements and analyses were made for sieved and unsieved ballotini surrounded by glycerol. Table 2 shows the data, η_{α} obtained from α , and η as measured using a Haake rheometer. The average discrepancy between η_{α} and η is about 10%; this is within expectation allowing for possible sources of uncertainty.

Non-Newtonian base fluids. The technique described above for the Newtonian base fluids was applied to ballotini supported by the non-Newtonian base fluids. These were a water-based clay gel made from Bentopharm, and the oil-based clay gel made from Carbogel. Figure 9 compares η_{α} with a high shear rate viscosity η_{∞} . This



Figure 8 Velocity versus ballotini volume fraction for $a_0 = 15.8 \,\mu\text{m}$ ballotini in glycerol at 20°C and 2.25 MHz

Base fluid	a ₀ (μm)	σ	$(lpha/\phi)$ (m ⁻¹)	η_{α} (mPas)	η (mPas)
PPG2025 (20°C)	31.5	0.40	1220 + 25	360 + 25	415 ± 10
PPG2025 (20°C)	30.5	0.35	1220 ± 25	450 ± 25	415 \pm 10
glycerol (22°C)	20.5	0.21	1510 ± 70	1230 ± 130	1210 ± 10
glycerol (22°C)	31.5	0.40	875 ± 80	1200 ± 200	1210 ± 10
glycerol (22°C)	30.5	0.35	875 <u>+</u> 80	1300 <u>+</u> 200	1210 <u>+</u> 10



Figure 9 Viscosity versus clay volume fraction. Diagonal crosses; η_{α} for Carbogel. Upright crosses; η_{α} for Bentopharm. Triangles; η_{∞} for Carbogel. Squares: η_{∞} for Bentopharm

latter quantity was obtained by measuring the shear stress τ as a function of the shear rate $\dot{\gamma}$ using a Carrimed rheometer. The $\tau(\dot{\gamma})$ data were then fitted to the Casson relation

$$\tau^{1/2} = \tau_0^{1/2} + \eta_{\infty}^{1/2} \dot{\gamma}^{1/2} \tag{25}$$

to obtain η_{∞} ; τ_0 is the yield stress. Although a fair agreement exists between η_{α} and η_{∞} for the oil-based Carbogel, $\eta_{\alpha}/\eta_{\alpha} \sim 3$ for the water-based Bentopharm.

This discrepancy was further investigated by measuring c for the two non-Newtonian suspensions, and applying the analysis described earlier, using Equation (24) with $K_3 = 5.2$ to account for particle concentration, to obtain a viscosity η_c . Figures 10 and 11 show the fit of data to theory, giving $\eta_c = 188$ mPa s for the Bentopharm and $\eta_c = 125$ mPa s for the Carbogel, at clay volume fractions of 0.025 and 0.037, respectively. At this clay volume fraction, η_{α} was approximately 4 mPa s and 10 mPa s. The large discrepancy between η_{α} and η_{c} , for both non-Newtonian fluids, is resolved if these fluids are allowed some shear elasticity G. This quantity is usually associated with fluids which have a yield stress τ_0 . It represents the Hookean response to small stresses of the structure originating from weak attractive bonds between clay particles. It is this structure which is destroyed at shear stresses exceeding τ_0 . Ultrasonic stresses in our experiments were negligible compared with τ_0 .

Assuming this interpretation, the theory presented in the section on the viscoelastic base fluid shows that the skin depth δ has to be replaced by $\delta' - \delta''$ in the equations for c, and by $\delta' + \delta''$ in those for α . Hence, if η_{α} and η_{c} are obtained from experimental data by interpretation



Figure 10 Velocity versus ballotini volume fraction for ballotini of $a_0 = 19.9 \,\mu\text{m}$ in 2.5% by volume Bentopharm suspension at 22°C and 5 MHz. Markers show data; line shows theory



Figure 11 Velocity versus ballotini volume fraction for ballotini of $a_0 = 19.9 \ \mu m$ in 3.7% by volume Carbogel suspension at 22°C and 5 MHz. Markers show data; line shows theory

through a purely viscous model, as done above, then

$$\frac{\eta_c}{\eta_a} = \left(\frac{\delta' + \delta''}{\delta' - \delta''}\right)^2 = \frac{(1+Q^2)^{1/2} + Q}{(1+Q^2)^{1/2} - Q}$$
(26)

A useful simplification of Equation (26) is that $\eta_c/\eta_a = 4Q^2 + 2$ to within a 3% accuracy for Q > 1. As Q > 0 for a viscoelastic fluid then Equation (26) explains the experimentally-found result that $\eta_c > \eta_a$ for the Bentopharm and the Carbogel clay fluids. Using the previous results

of 47 and 12.3 for η_e/η_α for these fluids then Equation (26) gives Q = 3.4 and 1.6 for the Bentopharm and Carbogel fluids, respectively. If, pro tem, η_∞ , from Figure 9 is taken to approximate the fluid viscosity, an elasticity of G = 2 MPa and 0.5 MPa is obtainable for the Bentopharm and Carbogel fluids, respectively. These are not dissimilar to $G = 18 \pm 5$ MPa found at 5 MHz for a waterbase clay by a previous method⁵. The closer agreement shown in Figure 9 of η_α with η_∞ for Carbogel, compared with the discrepancy between them for Bentopharm, may hence be related to the greater elasticity of the Bentopharm gel.

Discussion

For glass ballotini supported by Newtonian fluids, where the scattering is in the Rayleigh region, and where the viscous skin depth is small compared with the particle radius, our measured values of velocity and attenuation are in close agreement with the expressions for these quantities given by Ament⁸ and Urick⁶, respectively. For ballotini suspended in non-Newtonian fluids, the measured velocity and attenuation can be understood if allowance is made for the elasticity of the suspending fluids. It follows that care should be taken when using acoustic waves to investigate complex fluids where the continuous phase may be not purely viscous, e.g. by polymer gels in foods or by clay gels in drilling muds.

Recently, Derjaguin *et al.*¹⁵ have given experimental evidence that several molecular fluids possess an elasticity, typically in the $10^4 - 10^5$ Pa range. For our molecular fluids, e.g. glycerol, such elasticity would give $Q \sim 0.1$ at 1 MHz, and hence would be undetectable as a difference between η_{α} and η_c in measurements where the fluid supports ballotini, and this is concordant with our results for these fluids. However, for water or similar low-viscosity fluids, $Q \sim 10$ would be similar to that found by us for ballotini suspended in the viscoelastic clay fluids. Such experiments would form a test of the assertion of Derjaguin *et al.*¹⁵

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